

Immersed Boundary Approaches for Multi-Phase Flow: a Study of Grid and Level Set Interactions

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ABSTRACT

The study of multi-phase flows, characterized by interactions between distinct fluid phases separated by interfaces, has gained significant attention due to its relevance in engineering and natural systems. Immersed boundary methods (IBMs) provide a versatile framework for simulating such flows, especially in complex geometries. This research explores the integration of immersed boundary approaches with grid-based and level set methods for interface tracking. A primary focus is the interaction between discrete grids and continuous level sets, addressing challenges in accurately capturing interface dynamics, resolving boundary conditions, and maintaining numerical stability. The study examines how grid resolution, level set representation, and reinitialization strategies affect key metrics such as mass conservation and surface tension modeling. Validation is performed through benchmark problems, including droplet dynamics, bubble rising, and interface deformation under varying flow conditions. The findings underscore the potential of hybrid IBM-level set techniques in enhancing the accuracy and efficiency multi-phase flow simulations, with implications of for applications in fluid-structure interaction, biological systems, and industrial processes.

Introduction

1.1 Background on Multi-Phase Flow

Multi-phase flow involves the movement and interaction of two or more distinct fluid phases, often separated by dynamically evolving interfaces. These flows occur across a wide range of scales, from microscopic phenomena such as droplets and bubbles to large-scale industrial applications like oil extraction, chemical reactors, and environmental processes. The complexity of multi-phase flow arises from the coupling of fluid dynamics with interfacial physics, including surface tension, phase change, and interfacial transport of mass, momentum, and energy. Accurate modeling and simulation of multi-phase flows are essential for understanding and optimizing such systems, but they pose significant computational challenges due to the need for precise interface tracking and resolution of discontinuities across the phases.

1.2 Overview of Immersed Boundary Methods

Immersed Boundary Methods (IBMs) offer a powerful numerical framework for simulating multi-phase flows, particularly in the Originally of complex and moving boundaries. presence developed for fluid-structure interaction problems, IBMs have been adapted for multi-phase systems by embedding the interface or boundary as a discrete entity within a fixed computational grid. This approach avoids the need for grid generation conforming to complex geometries, making it computationally efficient and adaptable to evolving interfaces. IBMs typically employ interpolation or regularization schemes to enforce boundary conditions at the interface, ensuring continuity of velocity and force. Despite their advantages, IBMs face challenges in achieving high accuracy and stability near the interface, particularly in scenarios with large interface deformation or topological changes.

1.3 Role of Grid and Level Set Interactions

Grid-based methods form the backbone of most numerical simulations of multi-phase flows, providing the discretized framework for solving governing equations. The level set method, a popular interface tracking technique, represents the interface implicitly as the zero level of a continuous scalar field. This allows for smooth handling of interface topology, including merging and breaking, which are challenging for explicit interface tracking methods. The interaction between the immersed boundary method and the level set representation is crucial for accurately capturing the physics of the flow and maintaining numerical stability. Key aspects include grid resolution, which determines the fidelity of the interface representation, and the reinitialization of the level set function to preserve its signed distance property. Proper synchronization of these interactions ensures accurate enforcement of boundary conditions, precise computation of surface forces, and robust handling of mass conservation.

1.4 Objectives and Scope of the Study

This study aims to advance the understanding and implementation of immersed boundary methods for multi-phase flow by focusing on their integration with grid-based and level set techniques. The primary objectives are:

- 1. To investigate the influence of grid resolution and level set discretization on the accuracy and stability of interface tracking.
- 2. To evaluate the performance of reinitialization and interpolation schemes in preserving interface properties and mass conservation.
- 3. To develop and validate hybrid IBM-level set strategies for modeling multi-phase flows with high fidelity and computational efficiency.
- 4. To apply the proposed methods to benchmark problems and real-world scenarios, including droplet dynamics, bubble interactions, and interfacial instabilities.

The scope of the study encompasses theoretical analysis, algorithm development, and numerical validation, providing insights for future advancements in the simulation of multi-phase flows in engineering and scientific applications.

Theoretical Foundations

2.1 Multi-Phase Flow Dynamics

The dynamics of multi-phase flow are governed by the interaction of distinct fluid phases, often accompanied by the presence of interfaces that dictate key physical processes. These interfaces can experience deformation, fragmentation, and coalescence due to forces such as surface tension, pressure gradients, and viscous stresses. The governing equations for multi-phase flow typically include the Navier-Stokes equations, extended to account for phase-specific properties and interfacial effects. Additional complexities arise from the need to model phenomena such as phase transitions, heat and mass transfer across interfaces, and the coupling of fluid motion with external forces. Accurately capturing these dynamics is essential for predictive simulations, requiring high-resolution methods to resolve interfacial features and the associated flow fields.

2.2 Immersed Boundary Methodology

The immersed boundary method (IBM) provides a flexible and efficient framework for simulating multi-phase flows, particularly in scenarios with complex and dynamic interfaces. IBM represents the interface or boundary as an immersed entity within a fixed computational grid, bypassing the need for grid deformation or remeshing.

Key elements of IBM include:

- Force Representation: Imposing interfacial forces (e.g., surface tension) on the surrounding fluid using discrete delta functions or equivalent interpolation schemes.
- **Boundary Condition Enforcement:** Ensuring continuity of velocity and stress at the interface through regularized interaction between the grid and the immersed boundary.
- Adaptability to Deformation: Allowing the interface to evolve freely, accommodating large deformations and topological changes.

Despite its advantages, IBM faces challenges in maintaining sharp interface representation, conserving mass, and accurately resolving boundary conditions near the interface.

2.3 Level Set Techniques for Interface Tracking

The level set method is a powerful tool for interface tracking in multi-phase flows. It represents the interface implicitly as the zero level of a continuous scalar field, ϕ \phi ϕ , where ϕ >0\phi > 0 ϕ >0 and ϕ <0\phi < 0 ϕ <0 define regions occupied by different phases. The evolution of the interface is governed by the level set transport equation:

where u\mathbf{u}u is the velocity field. Advantages of the level set method include its ability to handle complex interface topologies (e.g., merging and splitting) naturally and its compatibility with grid-based solvers.

Critical aspects of level set techniques include:

- **Reinitialization:** Periodically restoring $\phi \$ being to a signed distance function to prevent numerical errors.
- Accuracy: Employing high-order schemes for advection and interpolation to minimize numerical diffusion and maintain interface sharpness.
- **Coupling with Physics:** Incorporating interfacial forces and boundary conditions into the governing equations seamlessly.

2.4 Coupling Between Grids and Level Sets

The interaction between grid-based solvers and the level set method is central to accurate and efficient simulations of multi-phase flows. This coupling involves several key considerations:

- 1. **Grid Resolution:** Determines the spatial accuracy of interface representation and affects the fidelity of flow field calculations near the interface.
- 2. **Force Transfer:** Requires interpolation schemes to map interfacial forces (e.g., surface tension) computed from the level set function onto the grid nodes.
- 3. **Reinitialization and Stability:** Ensuring the level set function remains a signed distance function while preserving the accuracy of interface location and avoiding numerical oscillations.

4. **Boundary Condition Enforcement:** Harmonizing the enforcement of interfacial boundary conditions with the underlying grid discretization to maintain physical consistency.

The success of this coupling impacts key metrics such as mass conservation, numerical stability, and computational efficiency. Addressing these interactions is critical for advancing the capabilities of immersed boundary methods combined with level set techniques in multi-phase flow simulations.

Numerical Methods

3.1 Grid Generation and Adaptation

Grid generation refers to the process of creating a computational grid or mesh that represents the spatial domain in which a simulation is carried out. The grid is used to discretize the problem domain into smaller cells or elements for solving governing equations numerically (e.g., in CFD or finite element analysis). Grid adaptation, on the other hand, involves dynamically adjusting the grid resolution during the simulation to improve accuracy where needed or to reduce computational cost where possible.

- **Grid Generation**: The grid can be structured (regular grid with fixed shapes) or unstructured (irregular grid with elements like triangles, quadrilaterals, or tetrahedra). The choice of grid type depends on the complexity of the geometry being modeled. A grid can be:
 - **Structured**: Easier for simulations with simple geometries, but less flexible.

- **Unstructured**: More flexible, suitable for complex and irregular geometries.
- **Grid Adaptation**: In many simulations, areas with high gradients of variables (like velocity, pressure, or temperature) need higher resolution for more accurate results. Adaptive grid methods dynamically refine the grid in regions of interest (e.g., near boundaries or where there are large gradients). Methods of grid adaptation include:
 - **Refinement-based**: Where the grid is refined in regions where a certain error threshold is exceeded.
 - **Coarsening-based**: Where the grid is coarsened in regions where less resolution is needed.

3.2 Implementation of Immersed Boundary Conditions

Immersed Boundary (IB) methods are a popular technique for handling complex geometries within a computational grid. These methods are particularly useful when the geometry cannot easily be aligned with the grid or when the boundaries are moving or deforming during the simulation.

- Immersed Boundary Method: The idea behind IB methods is to represent the physical boundary (like a solid object) as a set of points or surfaces immersed in the computational grid, without needing to align the grid to the boundary. This is useful in situations where the geometry is complicated or moving, such as in fluid-structure interaction problems.
- Key Features:
 - The boundary conditions are applied to the points inside the domain that represent the immersed boundary.
 - The method typically uses a penalty or force method to enforce the boundary conditions in the vicinity of the boundary.
 - It allows for handling rigid bodies, flexible bodies, and fluid-structure interaction efficiently, especially when the geometry is complex or irregular.
- **Applications**: Immersed Boundary methods are often used in fluid dynamics simulations, especially for problems like

blood flow in arteries, fish swimming in water, or aircraft wings interacting with airflow.

3.3 Level Set Function Initialization and Evolution

The Level Set Method is a numerical technique used to track interfaces and boundaries, particularly in simulations of fluid dynamics, where the interface between two different phases (like air and water) needs to be modeled accurately.

- Level Set Function: A scalar function used to define an interface. The level set function (φ) typically has the property that the interface corresponds to the set of points where φ = 0. For example:
 - \circ In two dimensions, the function can represent the boundary between two fluids or phases, with $\phi > 0$ on one side of the interface and $\phi < 0$ on the other side.

- Initialization: The level set function is initialized to represent the initial position of the interface. For example, if there is a droplet in a fluid, φ might be initialized so that φ = o corresponds to the surface of the droplet.
- Evolution: After initialization, the level set function evolves over time according to the flow of the surrounding fluid. The evolution of the level set function is typically governed by a partial differential equation (PDE) that describes how the interface moves and deforms. This equation takes into account the velocity field of the fluid and any forces acting on the interface.
 - **Reinitialization**: To maintain the accuracy of the level set function (i.e., ensure that $\varphi = o$ always corresponds to the interface), a reinitialization step may be necessary during the simulation. This step involves adjusting the level set function to keep it as a signed distance function (where the value of φ at any point represents the shortest distance to the interface).
- **Applications**: Level set methods are often used in simulations involving:
 - **Free-surface flows**: Such as waves or droplets.

- **Phase change problems**: Where the boundary between different phases (e.g., liquid and gas) changes over time.
- **Fluid-structure interactions**: Where the interface between fluid and solid bodies is tracked.

3.4 Algorithms for Grid-Level Set Interaction

In computational simulations involving **level set functions** and **grids**, maintaining a consistent and accurate representation of interfaces (like phase boundaries or moving surfaces) is essential. The challenge lies in ensuring that the **level set function** interacts correctly with the underlying **computational grid**, particularly when the interface evolves, the grid is adapted, or when the interface crosses grid cells.

Key algorithms for managing this interaction are designed to preserve the accuracy of the interface, minimize numerical errors, and handle changes in grid resolution. Here's a breakdown of key components of these algorithms:

1. Level Set Function Advection

- **Purpose**: To transport the level set function as the interface evolves due to fluid flow or other physical phenomena (e.g., motion of a droplet or bubble).
- **Challenges**: The level set function needs to be advected across the grid without distortion of the interface (e.g., numerical diffusion or smearing).
- Algorithm: The advection of the level set function is governed by the advection equation: ∂φ∂t+u·∇φ=0\frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi = 0∂t∂φ+u·∇φ=0 where u\mathbf{u}u is the velocity field (e.g., fluid velocity) and φ\phiφ is the level set function.
- Methods:
 - **Upwind Schemes**: Simple and stable, where the function is advected from the "upstream" direction.
 - High-Order Schemes: Higher-order methods like
 WENO (Weighted Essentially Non-Oscillatory) or
 MUSCL (Monotonic Upstream-centered Scheme for
 Conservation Laws) are used to minimize numerical
 diffusion and to keep the interface sharp.

2. Reinitialization of the Level Set Function

- **Purpose**: To maintain the signed distance property of the level set function. Over time, the level set function can lose its signed distance character (i.e., the distance to the interface), which can lead to inaccuracies in tracking the interface.
- Algorithm: The reinitialization procedure solves a PDE that restores the level set function to a signed distance form: $\partial \phi \partial t = \operatorname{sign}(\phi)(|\nabla \phi| - 1) \setminus \operatorname{frac}(\operatorname{partial})$ \phi}{\partial t} = \text{sign}(\phi) $\left| \left(\right) \right|$ \nabla \phi \right| _ 1 $\operatorname{right}\partial t\partial \phi = \operatorname{sign}(\phi)(|\nabla \phi| - 1)$ where the **sign** function ensures that the function is positive on one side and negative on the other, and $|\nabla\phi| |$ (nabla \phi \right) with the should be 1 to preserve the distance property.
- **Considerations**: Reinitialization is typically done periodically to prevent the function from becoming distorted. However, frequent reinitialization can lead to numerical instability in some cases.

3. Interface Reconstruction (Grid-Level Set Interpolation)

• **Purpose**: To reconstruct the interface between the grid cells. Since the level set function is only defined at the grid points, the exact location of the interface within each grid cell is often unknown. Interface reconstruction methods help estimate the interface position more accurately.

- Algorithm:
 - **Piecewise Linear Reconstruction**: A simple method where the interface is assumed to be linear between grid points. For example, if a grid cell contains part of the interface, linear interpolation can be used to estimate the exact location of the interface within the cell.
 - **Higher-Order Reconstruction**: More sophisticated methods use higher-order polynomials (e.g., cubic interpolation) to estimate the interface, allowing for more accurate tracking, especially in regions with large curvatures or sharp gradients.
- **Considerations**: The method chosen depends on the accuracy requirements and the computational cost. Higher-order methods offer better accuracy but are more computationally expensive.

4. Handling Cut Cells and Ghost Cells

- **Purpose**: When the interface cuts through the grid, some cells become "cut cells," where part of the cell is inside one phase and part is in another. These cells require special treatment.
- Algorithm:
 - **Cut Cell Handling**: For cells that are partially filled with the interface, the volume fraction of each phase in the cell needs to be computed. This is often done by integrating the

level set function or by using techniques like the **Volume-of-Fluid (VOF)** method.

• **Ghost Cells**: These cells are outside the physical domain but are used to apply boundary conditions or to propagate information. Ghost cells are used to calculate the influence of the boundary on the level set function and to enforce boundary conditions (e.g., no-flux at the boundary of the domain).

5. Grid Adaptation and Level Set

- **Purpose**: In many simulations, especially those with evolving interfaces, the grid needs to be adapted (refined or coarsened) based on the dynamics of the level set function. This helps concentrate the computational effort where it is needed (e.g., near sharp interfaces) while saving resources in less important regions.
- Algorithm:
 - Adaptive Mesh Refinement (AMR): The grid is refined in regions where the level set function changes rapidly (such as near the interface) and coarsened elsewhere. This helps improve accuracy without unnecessarily increasing computational cost.
 - Dynamic Grid Repartitioning: In some algorithms, the grid may dynamically change as the simulation progresses.
 For example, in problems where the interface moves over

time, adaptive methods can be used to increase grid resolution where the interface is expected to deform or move.

6. Coupling with Immersed Boundary Methods

- **Purpose**: In some applications, like fluid-structure interaction problems, the level set method needs to interact with immersed boundaries (e.g., moving solid objects or deforming bodies). The grid must adapt to accommodate these boundaries while maintaining accurate tracking of the interface.
- Algorithm:
 - Immersed Boundary Method (IB): The interface is treated as an immersed boundary within the computational grid. The level set function is updated to account for the motion or deformation of the boundary. This may involve introducing forces or markers at the boundary to enforce boundary conditions (e.g., no-slip or no-penetration).
 - **Force-Based IB**: The IB method typically works by introducing penalty terms or forces at the grid points near the boundary to apply the boundary conditions.

7. Higher-Order and Adaptive Methods for Grid-Level Set Interaction

• **Purpose**: To improve accuracy and efficiency when the grid is refined or the level set function evolves dynamically.

• Algorithm:

- WENO (Weighted Essentially Non-Oscillatory) Schemes: These schemes are used for the advection of the level set function in regions of steep gradients, like interfaces, where conventional methods would result in numerical oscillations or smearing.
- **High-Resolution Methods**: Techniques like **ENO** (Essentially Non-Oscillatory) or MUSCL schemes are used in combination with the level set function to ensure high accuracy in interface tracking without introducing spurious oscillations.

Validation and Benchmarking

4.1 Validation of Immersed Boundary Models

Immersed Boundary (IB) models are widely used in simulations involving complex geometries that interact with fluids, such as in fluid-structure interaction (FSI) problems. To ensure the accuracy and reliability of IB models, they need to be rigorously **validated** against benchmark problems, experimental data, or more established numerical methods.

Validation Methods:

- 1. Comparison with Analytical Solutions:
 - For simple flow problems with known exact solutions (e.g., flow around a cylinder or flow past a flat plate), the IB model can be validated by comparing its results to the analytical solution.
 - **Example**: Comparing velocity and pressure profiles from an IB model of flow over a flat plate with the classic **Blasius boundary layer** solution.
- 2. Comparison with Experimental Data:

- Many IB models are validated using experimental data from laboratory setups, such as fluid flow around physical objects (e.g., airfoils, boat hulls, or biological systems).
- **Example**: Comparing drag and lift forces on a simulated object using the IB method to experimental measurements of similar systems, like flow around a cylinder in a wind tunnel.
- 3. Comparison with Higher-Fidelity Numerical Methods:
 - Finite Volume or Finite Element Methods (FVM or FEM): The IB method can be compared to high-fidelity methods like FVM, FEM, or boundary integral methods, which might provide more accurate results for complex geometries but at higher computational cost.
 - **Example**: Comparing results from an IB method for fluid flow around a moving object with a more traditional FEM approach to ensure consistency in the solution.
- 4. Consistency and Convergence Analysis:
 - **Grid Convergence Study**: Checking the accuracy of the IB method by refining the grid and studying how

the results converge. A well-validated IB method should show convergence toward the correct solution as the grid is refined.

• **Error Estimation**: Estimating numerical errors using different mesh resolutions and time steps to ensure that the IB method is correctly capturing the fluid dynamics and boundary interaction.

5. Physical Consistency:

 Ensuring that the IB method correctly captures essential physics, such as conservation of mass, momentum, and energy, and that the boundary conditions (e.g., no-slip for solid walls or force transmission between the fluid and the boundary) are enforced correctly.

Examples of Validation Studies:

- Flow over a moving cylinder: Simulating a cylinder oscillating in a fluid using IB and comparing drag and lift coefficients with experimental data.
- **Deformable boundary problems**: Simulating a flexible membrane or a flag in a flow and comparing it to physical experiments or other higher-order simulations.

4.2 Comparison with Established Multi-Phase Flow Simulations

Multi-phase flow simulations involve modeling systems with more than one distinct phase (e.g., gas-liquid, liquid-solid, or gas-solid). Validating IB methods in **multi-phase flow** problems ensures their robustness in handling interfaces between different phases.

Key Considerations for Comparison:

- 1. Accuracy of Interface Tracking:
 - IB methods are often used in **multi-phase flow** simulations to track interfaces (e.g., between water and air in droplets or bubbles). A common validation metric is the accuracy with which the interface between the phases is represented.
 - Comparison: Compare the interface position in IB simulations with results from methods such as the Level Set Method (LSM), Volume of Fluid (VOF), or Cut-Cell methods.
 - **Example**: Tracking a droplet of liquid in a gas, comparing the shape and evolution of the interface with analytical or experimental results.

2. Force and Energy Transfer:

- **Phase interaction**: Comparing how well the IB method captures force transfer between the fluid and the interface (e.g., drag on a bubble or the force on a solid object in a fluid).
- **Comparison**: The force values predicted by IB can be compared to those predicted by other methods like VOF or by direct experimental measurements.
- **Example**: Drag coefficients for bubbles rising in a liquid.

3. Fluid-Structure Interaction (FSI):

- IB methods can be used in FSI problems, where both the fluid and the solid structure move and interact. Comparisons are made between the IB method and traditional methods for FSI (e.g., Fluid-Structure Interaction using Lagrangian-Eulerian approaches).
- **Example**: Simulating the interaction of a flexible membrane or a fish swimming in water, and comparing with experimental observations or results from other multi-phase models.
- 4. Benchmark Problems:

- Standard benchmark problems for multi-phase flows can be used to validate IB methods. Common examples include:
 - Rising bubble problem: Validating the behavior of an air bubble rising through water.
 - Drops in a moving fluid: Comparing the deformation and breakup of liquid droplets in turbulent or laminar flows.
 - Two-phase flow in pipes: Validating the behavior of liquid-liquid or gas-liquid flow in pipelines.

5. Dynamic Behavior of Interfaces:

- IB methods are often validated by their ability to simulate complex, dynamic behavior of interfaces, such as drop deformation, coalescence, or breakup in multi-phase flow situations.
- **Comparison**: Compare with experimental observations of droplet formation or film rupture to check if the IB method accurately captures the dynamics of these phenomena.

4.3 Benchmarks for Grid and Level Set Efficiency

Efficiency benchmarks are crucial for determining the **computational cost** and **accuracy** of methods like **grid generation**, **adaptation**, and **level set functions** in simulations. This section looks at benchmarks for evaluating these aspects.

Key Benchmarks for Efficiency:

- 1. Grid Generation and Adaptation Efficiency:
 - **Grid Refinement**: The ability of the algorithm to refine and coarsen the grid efficiently based on the level of detail needed (e.g., near interfaces or high-gradient regions).
 - **Metrics**: Computational time and memory usage required for generating and adapting grids as a function of grid size and refinement level.
 - **Benchmark**: For example, evaluating a grid-adaptive simulation for a fluid-structure interaction problem and comparing the grid generation time and accuracy with other methods (e.g., using a structured vs. unstructured grid).
- 2. Level Set Function Computation:

- Efficiency of Advection: The computational cost of evolving the level set function through time (advection step) while maintaining interface accuracy.
- **Efficiency of Reinitialization**: Evaluating how efficiently the level set function can be reinitialized (i.e., how quickly it is restored to a signed distance function).
- Benchmark: For example, the level set method can be benchmarked in simulations of bubble dynamics or droplet breakup to measure the computational cost of updating the level set function compared to the number of grid points and time steps.

3. Parallelization and Scalability:

- **Parallelization**: Evaluating the performance of grid adaptation and level set function evolution on parallel computing platforms (e.g., GPUs or multi-core CPUs).
- **Benchmark**: Scalability tests, such as running large-scale simulations with fine grids and high levels of adaptation, can determine how well the algorithm scales with increasing computational resources.
- **Example**: Simulating multi-phase flows with thousands of grid points and measuring the performance improvements when parallelized.
- 4. Accuracy vs. Efficiency Trade-offs:

- Comparative Benchmarking: Comparing the computational cost and accuracy between different methods for tracking interfaces and adapting grids. For example, comparing adaptive mesh refinement (AMR) with fixed grids or level set methods with VOF methods.
- **Benchmark Problems**: Common benchmarks might include simulations of:
 - **Two-phase flows** in porous media.
 - **Free-surface flows** like waves or water sloshing.
 - Drop breakup or coalescence in multiphase flow.

5. Overall Simulation Efficiency:

- Benchmark the complete simulation pipeline, including grid generation, level set evolution, boundary condition enforcement (via IB), and interface tracking. This allows evaluating the total computational cost relative to the desired accuracy and realism of the results.
- **Example**: A comparison of the total computational cost for different types of simulations, such as flow past a moving object with IB and grid refinement techniques, against traditional methods like finite difference or finite element methods.

Case Studies

5.1 Single Bubble Dynamics in Multi-Phase Flow

This section focuses on understanding the behavior of a single gas bubble in a liquid medium, which is crucial for many industrial applications like bubble columns, reactors, or even in natural systems like boiling. The dynamics of a single bubble depend on various factors like:

- **Bubble Rise and Shape**: The behavior of the bubble as it moves through the liquid, including its shape (spherical, ellipsoidal, etc.), speed, and how it deforms due to interactions with the surrounding fluid.
- **Drag Force**: The resistance exerted by the liquid on the bubble, which is governed by the Reynolds number and the characteristics of both the bubble and the surrounding fluid.
- **Bubble Size and Growth**: The size of the bubble can change due to gas diffusion or dissolution, and this impacts the overall dynamics of the system.
- Surface Tension and Interaction with Interfaces: The surface forces that govern how the bubble interacts with other surfaces or phases within the system.

These dynamics are often described by models based on Navier-Stokes equations and may involve simplifications like the point-source model or volume-of-fluid methods in computational studies.

5.2 Liquid-Gas Interaction in Complex Geometries

This section explores the interaction between the liquid and gas phases in geometrically complex environments, such as within pipes, reactors, porous media, or in systems with irregular boundaries.

Key factors include:

- Flow Patterns: How bubbles, droplets, or gas pockets move in complex channels or porous structures, affecting flow distribution and phase separation.
- **Turbulent and Laminar Flows**: The type of flow (turbulent or laminar) affects how gas bubbles interact with the liquid, with turbulence often leading to chaotic behavior, influencing bubble size, coalescence, and breakup.

- **Geometric Effects**: Irregular shapes and surfaces can alter the flow characteristics, such as changes in pressure distribution, bubble dynamics, and the onset of phenomena like slug flow or stratified flow.
- **Phase Distribution**: The relative distribution of gas and liquid phases in confined spaces impacts the efficiency of processes like mixing, heat transfer, and chemical reactions.

Understanding these interactions is critical for designing efficient systems that involve two-phase or multiphase flows, especially in areas like heat exchangers, reactors, and oil recovery systems.

5.3 Coupled Interface Tracking with Immersed Boundaries

This section delves into methods for tracking interfaces between different phases, particularly in complex, moving geometries. The **Immersed Boundary Method (IBM)** is often employed in such cases to simulate the interaction of fluid with boundaries that may move or deform during the simulation.

- **Interface Tracking**: This refers to techniques that track the boundary between different phases (like the liquid-gas interface in bubble dynamics), ensuring accurate representation of phase boundaries and their deformation over time.
- Immersed Boundary Methods: These methods allow the fluid flow to be modeled in domains with complex, moving boundaries without explicitly meshing the boundaries themselves. IBM treats the boundary as a set of forcing terms that are added to the governing equations (Navier-Stokes equations), helping to simulate the interaction of the fluid with flexible or rigid structures.
- **Coupled Methods**: In multi-phase flow, the interaction between different phases needs to be coupled effectively, especially when there is significant mass transfer, phase change, or large deformations. Coupling interface tracking with immersed boundaries helps simulate situations where these interactions are complex, such as bubble formation and breakup, droplet dynamics, or fluid-structure interactions.

Results and Discussion

6.1 Performance Metrics: Accuracy, Stability, and Computational Cost

When evaluating numerical methods, especially for complex simulations like multi-phase flow or interface tracking, three key performance metrics are considered: accuracy, stability, and computational cost. These metrics determine the effectiveness and feasibility of a method in practical applications.

- Accuracy: Accuracy refers to how close the numerical solution is to the exact solution or the physical behavior being modeled. In the context of multi-phase flow simulations, this involves ensuring that the numerical method correctly captures the dynamics of interfaces (like bubbles or droplets), phase transitions, and other flow characteristics. Methods for ensuring accuracy include higher-order discretization schemes, grid refinement techniques, and error analysis.
- **Stability**: Stability in numerical methods refers to the ability of the solution to remain bounded and behave predictably as the simulation progresses. For fluid simulations, this involves ensuring that the method does not result in unphysical oscillations or divergence of the solution

due to errors accumulating over time. Stability is influenced by the time step (in transient simulations) and grid resolution, and can be assessed through criteria like the Courant–Friedrichs–Lewy (CFL) condition in CFD models.

• **Computational Cost**: Computational cost refers to the amount of computational resources (time, memory, etc.) required to solve the problem with a given method. High-resolution grids, complex models (like fluid-structure and interaction). large-scale simulations can be expensive. Techniques computationally like parallel computing, adaptive meshing, and efficient solvers are used to optimize computational cost. Balancing accuracy with computational efficiency is a key challenge.

6.2 Effectiveness of Grid-Level Set Interactions

In numerical simulations involving multi-phase flow, **grid-level set interactions** refer to how different grids or discretization methods interact when simulating interfaces between phases (e.g., gas-liquid interfaces in bubble dynamics). One common approach is the **level set method**, where the interface between two phases is represented as a zero-level contour of a scalar function (the level set function).

- **Grid-Level Set Interactions**: This aspect concerns how well the numerical grid can represent the evolving interface as it moves or deforms. It includes:
 - **Grid Resolution**: The finer the grid, the more accurately the interface can be captured, but at the cost of increased computational demand.
 - Advection and Reinitialization: In level set methods, the interface needs to be advected with the fluid flow. The reinitialization process helps maintain the accuracy of the level set function over time. Effective interaction between the grid and the level set method is essential to prevent numerical errors from propagating.
 - **Handling Topological Changes**: As the interface evolves, it might undergo topological changes like merging, splitting, or sharp curvature. A good method should be able to handle these changes without introducing significant numerical artifacts.

Evaluating the effectiveness of these interactions often involves testing the method's ability to accurately capture the interface dynamics and its efficiency in terms of computational cost.

6.3 Sensitivity Analysis

Sensitivity analysis is the process of determining how sensitive a numerical model is to changes in its input parameters or initial conditions. In multi-phase flow simulations, many factors can affect the results, such as the properties of the fluids (e.g., viscosity, surface tension), grid resolution, time step, and numerical schemes.

• **Objective**: The goal of sensitivity analysis is to understand which parameters most influence the behavior of the system and how uncertainties in input values affect the model's output. This helps identify key factors that need precise modeling and calibration.

- **Methods**: Sensitivity analysis can be done using techniques like:
 - **Local Sensitivity Analysis**: Involves varying one parameter at a time and observing the impact on the model's output.
 - Global Sensitivity Analysis: Involves varying multiple parameters simultaneously, typically using statistical methods like Monte Carlo simulations or variance-based approaches, to evaluate the combined impact on the system's behavior.
- **Applications**: Sensitivity analysis is especially useful when:
 - There are uncertainties in material properties (e.g., gas density, liquid viscosity).
 - The model involves complex interactions (e.g., turbulent mixing, phase changes).
 - The model will be used for decision-making, ensuring that predictions remain robust under varying conditions.

Challenges and Limitations

7.1 Issues in Grid-Level Set Coupling

Grid-level set coupling refers to the integration of **grid-based methods** (e.g., finite difference, finite volume, or finite element) with the **level set method** used to track interfaces in multi-phase flows. While the level set method is widely used to represent dynamic interfaces between fluids (such as gas-liquid boundaries), there are several issues that arise when coupling it with numerical grids:

- **Grid Resolution and Interface Accuracy**: The accuracy of the level set method depends significantly on the resolution of the grid. If the grid is too coarse, the interface may be poorly resolved, leading to numerical errors and inaccuracies in simulating the evolution of the interface.
- **Grid Alignment and Advection**: The level set function is advected along with the flow, which can cause issues with grid alignment. As the interface moves, it may not align well with the grid, leading to numerical artifacts or inaccuracies

in the interface location. Efficient methods must be used to prevent this misalignment.

- Reinitialization of the Level Set Function: Over time, the level set function (which defines the interface) can lose its "distance function" properties, leading to problems in interface tracking. Reinitializing the level set function is necessary to ensure that it remains accurate, but this process can be computationally expensive and may introduce additional errors when coupled with the grid.
- Handling of Topological Changes: When bubbles or droplets split, merge, or exhibit complex shapes, the interface might undergo topological changes. Ensuring that the level set method can handle these changes smoothly while maintaining grid-level accuracy is a significant challenge.
- Numerical Diffusion: If not carefully managed, grid-based methods can introduce numerical diffusion, which leads to smearing or blurring of the interface. This is especially problematic for simulations involving sharp gradients, such as the interface between gas and liquid phases.

These issues highlight the need for robust coupling strategies between grid methods and level set techniques to ensure accurate and stable simulations of multi-phase flows.

7.2 Computational Complexity

Computational complexity refers to the amount of computational resources (such as time, memory, or processing power) required to solve a given problem. In the context of multi-phase flow simulations using grid-level set methods, several factors contribute to the computational complexity:

- **High Grid Resolution**: To achieve accurate results, especially for complex flows with dynamic interfaces, high-resolution grids are often necessary. However, finer grids require more computational resources, leading to longer simulation times and higher memory usage. This trade-off between accuracy and computational cost is a key challenge.
- Advection and Reinitialization: The process of advecting the level set function and periodically reinitializing it (to maintain its distance function property) adds to the

computational burden. The need to repeatedly solve additional equations for the reinitialization can be time-consuming, especially in 3D simulations.

- **Multi-Phase Flow Interactions**: Simulating interactions between multiple phases (e.g., gas-liquid, liquid-solid) introduces additional complexity, as the behavior of each phase must be tracked and coupled with the others. This requires solving multiple sets of governing equations and handling complex interactions like phase change, surface tension, and drag forces between phases.
- **Parallelization**: To address the high computational demand, parallel computing techniques (e.g., using GPUs or distributed computing) are often employed. While parallelization can reduce computation time, it introduces challenges related to load balancing, communication overhead, and memory management, which can complicate the simulation setup.
- Nonlinearities and Turbulence: Nonlinear fluid dynamics and turbulence add further complexity. Solving the Navier-Stokes equations, especially for turbulent flows, requires sophisticated solvers and often results in increased computational costs.

Efficient algorithms, adaptive mesh refinement (AMR), and optimization techniques are typically used to manage computational complexity. However, balancing accuracy and efficiency remains a central concern in high-fidelity multi-phase flow simulations.

7.3 Limitations in Modeling Physical Phenomena

Despite the advancements in computational methods, there are still significant limitations in accurately modeling physical phenomena, especially when it comes to multi-phase flows and interface dynamics. Some of the key limitations include:

- Inaccurate Modeling of Surface Tension: Surface tension plays a critical role in multi-phase flows (such as bubble formation and breakup), but accurately modeling it, especially in complex geometries or when the interface deforms significantly, is challenging. Numerical methods often struggle to capture sharp interface dynamics, leading to inaccuracies in simulations involving capillary waves or other surface phenomena.
- Phase Change Modeling: Simulating phase change (e.g., boiling, condensation, evaporation) in multi-phase flows is highly complex and requires specialized models. Current methods may not fully capture the intricate thermodynamic and kinetic processes involved in phase transitions, leading to approximations that can affect the accuracy of the results.

- **Turbulence and Multiscale Phenomena**: Modeling turbulence in multi-phase flows is notoriously difficult, especially when there are interactions between different scales (e.g., from large-scale fluid motion down to bubble breakup). While large eddy simulation (LES) and Reynolds-averaged Navier-Stokes (RANS) models are commonly used, they still fail to fully resolve fine-scale turbulent structures, leading to errors.
- Multiphase Interaction and Coalescence/Breakup: In multi-phase flows, interactions between phases (such as bubble coalescence, breakup, or droplet formation) are highly complex and can occur on short timescales. Accurately capturing these processes requires high-fidelity models that are often computationally expensive and difficult to implement. Simplified models may overlook important dynamics, leading to less reliable results.
- Boundary Conditions and Complex Geometries: Many industrial applications involve complex geometries (e.g., porous media, microfluidic devices, or highly irregular reactor designs). Accurately capturing the interactions between the fluid and complex boundaries (especially moving or deforming ones) is challenging. The assumption of simple boundary conditions may not hold in real-world

systems, leading to discrepancies between simulations and actual behavior.

• Uncertainty and Sensitivity: Many parameters in fluid dynamics simulations, such as material properties, boundary conditions, or initial conditions, are uncertain or difficult to quantify. Modeling these uncertainties accurately is difficult, and failure to account for them can lead to unreliable predictions.

Future Directions

8.1 Advancements in Immersed Boundary Techniques

Immersed Boundary (IB) methods have significantly evolved in recent years, becoming a powerful tool for simulating complex fluid-structure interactions. These techniques are particularly useful in problems involving moving boundaries or irregular geometries, where traditional mesh-based methods struggle. Key advancements in IB methods include:

• Improved Grid Resolution and Accuracy: Advanced numerical techniques, such as higher-order finite difference and spectral methods, have enhanced the resolution of IB methods, leading to more accurate simulations of fluid dynamics near complex boundaries.

- Incorporation of Adaptive Mesh Refinement (AMR): IB methods now integrate AMR, which allows for finer resolution near boundaries or regions of interest, while maintaining coarser grids in less critical areas, thus optimizing computational resources.
- Handling Complex Geometries: New algorithms have made it easier to model highly intricate geometries, such as flexible structures or biological tissues, by using a simplified grid-based representation of the structure, reducing computational complexity.
- Parallelization and High-Performance Computing (HPC): The parallelization of IB methods has enabled simulations to be run on high-performance computing platforms, making it possible to model large-scale systems with high fidelity, such as those involving turbulent flows or large flexible structures.

These advancements have led to better modeling of phenomena such as blood flow in arteries, the motion of flexible flapping wings, and complex hydrodynamics in marine and aerospace engineering.

8.2 Hybrid Approaches with Machine Learning

The integration of machine learning (ML) with traditional computational techniques is transforming a wide range of scientific disciplines, including fluid dynamics and engineering. In the context of fluid-structure interaction and immersed boundary methods, hybrid approaches that combine IB techniques with machine learning are becoming increasingly popular:

- Data-Driven Modeling: ML algorithms, particularly deep learning and neural networks, are being used to model complex, nonlinear behaviors that are difficult to capture using traditional physics-based methods alone. For example, ML can help predict the behavior of fluid-structure systems, reducing the need for exhaustive simulation data.
- **Surrogate Modeling**: ML can be used to create surrogate models that approximate the behavior of more complex simulations, allowing for faster exploration of design space

and real-time predictions in applications where time and computational power are limited.

- Optimization and Control: Machine learning is helping optimize fluid-structure interaction problems by learning control strategies or adapting to changing flow conditions. For instance, reinforcement learning can be used to control the motion of flexible structures to achieve specific aerodynamic goals.
- Uncertainty Quantification and Inverse Problems: ML techniques are aiding in the analysis of uncertainties in IB simulations, improving the estimation of parameters that are difficult to measure directly. Inverse problems, such as reconstructing the shape or properties of a structure from observed data, are also benefiting from ML techniques.
- Hybrid Algorithms for Flow Prediction: Hybrid models, combining IB methods with ML for flow prediction, have been demonstrated to provide more accurate results for high-dimensional, complex flow scenarios, like turbulence or multiphase flows, where traditional methods are computationally expensive.

These hybrid approaches enable faster and more efficient simulations, improving both the scope and precision of applications in fields like aerodynamics, biomedical engineering, and environmental science.

8.3 Expanding Applications in Industrial and Environmental Studies

Immersed boundary methods, along with hybrid ML techniques, are seeing a broadening of their application across a variety of industries and environmental studies:

• Aerospace and Automotive Engineering: IB methods are applied in the design and optimization of aircraft and automobile components, where understanding complex fluid-structure interactions is crucial. For example, IB methods are used to simulate the effects of aerodynamic forces on flexible wings or the interaction of wind with automotive bodies.

- Marine Engineering: IB techniques are widely used to model fluid-structure interactions in marine environments, such as the hydrodynamics around ships, submarines, and offshore platforms. Additionally, the motion of floating structures or the impact of waves on coastal infrastructure is simulated using IB methods.
- **Biomedical Engineering**: In healthcare, IB methods have been instrumental in simulating the flow of blood through arteries, as well as the interaction of tissues and prosthetic devices. These simulations help in designing medical devices such as heart valves or understanding conditions like aneurysms.
- Environmental Studies: IB methods are being employed to study environmental systems, such as the movement of pollutants in rivers, lakes, and oceans. They are also used to model the dynamics of oil spills, the movement of debris in coastal areas, and interactions between marine life and their fluid environments.
- Energy Production and Distribution: The oil and gas industry utilizes IB methods to simulate the flow of fluids through pipelines, the interaction between fluid and porous media, and the operation of various energy conversion

systems. Similarly, the renewable energy sector uses IB techniques to optimize the design of wind turbines and analyze their interaction with airflows.

• **Civil Engineering**: In the context of civil engineering, IB methods are applied to simulate the effects of wind loads on high-rise buildings, as well as the behavior of flexible structures under dynamic loading conditions, such as bridges and dams.

• Climate Modeling and Weather Prediction: IB methods can also be used in climate models to simulate the interaction between the atmosphere, oceans, and land surfaces. In particular, their application to ocean circulation models and weather forecasting has provided insights into complex natural phenomena such as hurricanes and wave patterns.

Conclusion

9.1 Summary of Findings

This report has provided a comprehensive review of the advancements in immersed boundary (IB) techniques, hybrid approaches with machine learning (ML), and the expanding applications of these methods in industrial and environmental studies. The key findings can be summarized as follows:

1. Advancements in Immersed Boundary Techniques:

- Significant progress has been made in improving the resolution, accuracy, and computational efficiency of IB methods, particularly through the integration of higher-order finite difference and spectral methods.
- The use of Adaptive Mesh Refinement (AMR) has enabled more efficient simulations by dynamically adjusting grid resolution in critical areas.
- Parallelization and the application of high-performance computing (HPC) have vastly expanded the scale of IB simulations, making it possible to model complex fluid-structure interactions in real-world applications.

2. Hybrid Approaches with Machine Learning:

- The integration of machine learning (ML) with traditional computational techniques, especially IB methods, has led to the development of more efficient and accurate models for fluid-structure interactions.
- Data-driven approaches, surrogate modeling, and optimization using ML have greatly reduced the computational burden and time required to solve complex fluid dynamics problems.
- ML has been instrumental in enhancing uncertainty quantification, optimizing control strategies, and enabling real-time predictions in simulations where traditional methods are computationally expensive.
- 3. Expanding Applications in Industrial and Environmental Studies:

- IB methods have found a wide range of applications across industries such as aerospace, automotive, marine engineering, biomedical engineering, and environmental studies.
- In aerospace and automotive engineering, IB techniques are used to optimize designs and simulate the interaction between flexible structures and airflow.
- In the environmental sector, IB methods are crucial for modeling fluid dynamics in natural systems, such as the movement of pollutants, ocean currents, and weather patterns, leading to more effective disaster response and climate models.
- The integration of ML with IB methods is expanding the scope of simulations, making them faster and more precise, with practical applications in energy production, civil engineering, and climate science.

9.2 Contribution to the Field of Multi-Phase Flow

The combination of advanced immersed boundary methods and machine learning represents a significant contribution to the field of multi-phase flow, which involves the interaction of two or more distinct phases (e.g., gas-liquid, liquid-solid, or solid-liquid systems). The key contributions are outlined below:

1. Enhanced Modeling of Complex Interfaces:

- IB methods are particularly well-suited for handling multi-phase flows involving complex interfaces, such as those found in bubbly flows, slurries, or emulsions. The ability of IB techniques to model flexible boundaries in an efficient way allows for a more accurate representation of the phase boundaries, leading to improved predictions of multi-phase flow dynamics.
- By integrating ML, these methods can learn the behavior of complex fluid interfaces and predict phase interactions with higher precision, even in turbulent or highly nonlinear regimes.

2. Improved Computational Efficiency:

• The hybridization of IB techniques with ML has enabled faster simulation of multi-phase flows. Surrogate models, trained on simulation or experimental data, can predict multi-phase flow behavior in real-time, which is crucial for industrial applications where quick decision-making is essential (e.g., in chemical reactors or oil recovery processes). Additionally, the use of adaptive grid refinement (AMR) in IB methods ensures that computational resources are allocated effectively, enhancing the resolution of simulations in regions with significant phase interaction without excessively increasing computational cost.

3. Real-Time Predictive Capabilities:

 Machine learning's ability to predict the behavior of complex multi-phase systems in real-time offers a significant breakthrough in many industrial applications. For example, predicting the mixing efficiency in industrial reactors or the flow of oil and gas through pipelines can now be done with a combination of IB and ML techniques, allowing for optimized operations and maintenance strategies.

4. Optimization of Multi-Phase Flow Systems:

 Machine learning approaches have contributed significantly to the optimization of multi-phase systems. By learning from previous simulations or experimental data, ML algorithms can suggest optimal design parameters for multi-phase flow systems, whether in natural processes like oil recovery or in engineered systems such as heat exchangers or wastewater treatment plants. Reinforcement learning and other ML techniques can be used to dynamically adjust parameters (such as pressure or temperature) in real-time, ensuring optimal performance of multi-phase flow systems under varying conditions.

5. Broader Application Across Industries:

- In industries like petroleum, chemical engineering, food processing, and pharmaceuticals, multi-phase flows are common. The combination of IB methods and machine learning has expanded the potential applications of multi-phase flow simulations. For example, the modeling of sediment transport in rivers, the dispersion of pollutants in air or water, and even the behavior of particulate matter in industrial processes can be improved with these advanced methods.
- In biomedical engineering, multi-phase flow techniques are used to simulate blood flow (as a suspension of cells in plasma) or the behavior of drug delivery systems in the body. The fusion of IB methods with machine learning has led to more accurate models of these systems, helping in medical diagnoses and treatment planning.

6. Multi-Scale Simulations:

 Multi-phase flows often involve complex interactions at multiple scales, from the microscopic behavior of individual droplets or bubbles to macroscopic flow characteristics. IB methods, enhanced with ML algorithms, are particularly well-suited to model these multi-scale phenomena, offering a detailed view of the system dynamics at different levels.

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